

PLC Programming Guidelines

Dan Kandray January 30, 2020

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PLC Programming Guidelines



- I. Develop and Document the Project Plan
- II. Create a State Logic Diagram
- III. Organize Project Structure (Code) into Tasks, Programs and Routines
- IV. Develop Code for Reuse
- V. Standardize Naming Conventions
- VI. Develop Routine Logic Using State Logic Programming Methods
- VII. Simulate the ladder logic program of instructions to verify logic continuity
- VIII.Download and verify the program on the actual machine, workstation, or system being controlled.

I. Develop and Document the Project Plan

- 1. From project narrative, create a clear flowchart that details machine functions.
- 2. Develop a firm understanding of the process
- 3. Simplify the process as much as possible



I. Develop and Document the Project Plan Swagelok

4. List all anticipated physical inputs, outputs, parameters and alarms



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II. Create a State Logic Diagram



- 1. Identify the machine states and document the transitions (state selectors) on a State Logic Diagram
 - a) Each state is identifiable by the unique condition of the outputs



III. Organize Project Structure (Code) into Tasks, Programs and Routines

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1. Tasks

- a) Most code should reside in a continuous task
- b) Use periodic tasks for slower processes or when time based operations is critical
- c) Use event tasks for operations that require synchronization to a specific event
- 2. Programs
 - a) Separate distinguishable equipment or equipment functions into isolated programs
 - b) Control the execution order of the programs from Task (properties) Program Scheduler
 - c) Centralize Outputs into one program
 - d) Isolate reusable code and/or different programmers
- 3. Routines
 - a) Use ladder logic language in the routine and modularize code into subroutines.
 - b) Always place reset conditions in a branch preceding the set condition

III. Organize Project Structure (Code) into Tasks, Programs and Routines

Controller Organizer 🛛 👻 📮		Controller Organizer 👻 👎	×
Controller Organizer Controller MultiValve_St8_Seat_Tester Controller Tags Controller Fault Handler Controller Fault Handler Power-Up Handler Controller Fault Handler Controller Controller Controller Controller Controller Fault Handler Controlle	VS	Controller AutoHLT Controller Tags Controller Fault Handler Power-Up Handler Tasks HLT_Communications HLT_Comm_Main HLT_Comm_Main RTA_COM MainTask MainProgram AminTask MainProgram AminTask MainProgram Manual_HLT_cal_scrn Air_Reg_Calibration Air_Reg_Calibration Air_Reg_Calibration Air_Reg_Calibration Air_Reg_Calibration Air_Reg_Calibration Air_S Screen_Monitoring Air_S Screen_Monitoring Air_S Start_Conditions Air_Reg_Calibration Air_S Screen_Monitoring Air_Reg_Calibration Air_Reg_Calibration Air_Reg_Calibration Air_S Screen_Monitoring Air_Actuated_In_Out Air_Actuated_Valves Air_A	
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IV. Develop Code for Reuse



- 1. Use user-defined data types (UDTs) to group data
 - a) A UDT lets you organize or group data logically, so that all of the data associated with a device (such as a pressure transmitter or variable-frequency drive) can be grouped.
 - b) The tag names that you assign self-document the structure Programs
- 2. Use Add-On Instructions to create standardized modules of code for reuse across a project.
 - a) Used to encapsulate a specific or focused operation or function
- 3. Use subroutines to reuse code within a program
 - 1. Can pass UDTs
 - 2. Can only be called from with the program they reside

		Data Type: MODBUS_READ						
		Name		me: MODB	MODBUS_READ		Data Type Size: 36 by	
IDT Fxan	nnle	hle		Des	cription:			
				Me	mbers:			
				-1	Name	Data Type	Description	
					TRIO_ACK	INT	12	
Data Types					STEP	INT		
🝓 User-Defined					STATUS	INT		
					ERROR	INT		
100 COMMAS					CMD ACK	INT		
					CMD_ACK	INT		
CYCLE_DATA			-		X_LEF1_POS	INT		
					X_RIGHT_POS	INT		
					Z_POS	INT		
END CONN HOLD C	UR				X_LEFT_ENC_	POS INT		
19 MODELIS READ					X_RIGHT_ENC	POS INT		
	•				Z_ENC_POS	INT		
MODBUS_WRITE					LEFT_DRIVE	INT		
	cture				RIGHT DRIVE	INT		
100 March 1 Control					Z DRIVE	INT		
					TRIO EPP LIN			
							INT	
				_//-	TRIO_ERR_NC	INT		
A Controller Tags - MultiValve St8 Seat	Tester(controller)				ABORT	INT		
	All T				🕂 Add Merni	er		
Scope: In Multi Valve_St8_: V Show:			×	<u> </u>				
Name	Alias For	Base Tag	Data Type <u></u> A Dese	iptic				
			MODRUS DEAD					
THEAD THIO DATA				_			ОК	Cancel Apply Help
			MODDOJ WHITE					
			MODBUS WRITE		Read Write			
UERIFY_TRIO_DATA URITE_TRIO_DATA URITE_TRIO_DATA URITE_TRIO_CHK_OK			MODBUS_WRITE		Read/Write Read/Write			
E-VERIFY_TRIO_DATA			MODBUS_WRITE OK_TO_RUN OP_NAME		Read/Write Read/Write Read/Write			
VERIFY_TRIO_DATA WRITE_TRIO_DATA AOI_CHK_OK ooi_op_name F-COMMS			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS		Read/Write Read/Write Read/Write Read/Write			
E-VERIFY_TRIO_DATA E-WRITE_TRIO_DATA E-AOI_CHK_OK E-aoi_op_name E-COMMS E-SEND_DATA			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS PLC_FROM_SLA		Read/Write Read/Write Read/Write Read/Write Read/Write			
			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS PLC_FROM_SLA PLC_TO_SLAVE		Read/Write Read/Write Read/Write Read/Write Read/Write Read/Write			
			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS PLC_FROM_SLA PLC_TO_SLAVE REAL		Read/Write Read/Write Read/Write Read/Write Read/Write Read/Write			
			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS PLC_FROM_SLA PLC_TO_SLAVE REAL REAL REAL		Read/Write Read/Write Read/Write Read/Write Read/Write Read/Write Read/Write			
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			MODBUS_WRITE OK_TO_RUN OP_NAME PLC_COMMS PLC_FROM_SLA PLC_TO_SLAVE REAL REAL REAL REAL REAL		Read/Write Read/Write			

Add-On Instruction Example





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- 1. Controller
 - Area/Unit +Type (Abreviation)
 - Example: Mixing_CPX
 - Note abbreviation is for CompactLogix PLC
- 2. Controller Project
 - Controller name, the letter C, 1-digit major revision number, underscore, 2-digit minor revision number
 - Example: Mixing_CPX_C2_07.ACD

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- 3. I/O Module
 - Controller name, underscore, abbreviation of rack location (L=local, R=remote), underscore, the letter S, 2-digit slot number, underscore, abbreviation of function
 - Analog input: Al
 - Analog output: AO
 - Discrete input: DI
 - Discrete output: DO
 - Example:
- Mixer123 Controller, Local chassis, Slot 4, Analog Output Module Name:
 - M123_CPX_L00_S04_AO
- Mixer123 Controller, Remote chassis #2, Slot 5, Discrete Input Module Name:
 - M123_CPX _R02_S05_DI

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- 4. Tags
 - The tag name should be meaningful to future application users
 - Utilize a prefix with the abbreviation of the type of tag
 - Input tag: I_tag name
 - Output tag: O_tag name
 - Machine State: Sta_tagname
 - Parameter: Par_*tagname* (Variables that are received from an external source that can be internal or external to the program)
 - Set point: Set *tagname* (Variables received from an operator or HMI and are not part of an external source)
 - Value: Val_tagname (Designates a value that might not be the primary output of the structure)
 - Report: Rpt_*tagname* (Designates a value that is typically used for reporting.)
 - Examples: I_

I_GRN_PB Sta_Idle Set_TankHILevel Rpt_Tank1Temp O_GRN_LT Par_TargetFillLevel Val_midpoint

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5. UDT

- A UDT lets you organize or group data logically, so that all of the data associated with a device (such as a pressure transmitter or variable-frequency drive) can be grouped.
 - You can mix data types, such as real or floating point values, counters, timers, arrays, Booleans, and other UDTs, within one UDT.
 - You can copy a UDT from one project to another, and even from one Logix controller type to another.
 - A UDT is self-documenting based on the tag names you assign, and provides a logical representation of parts or subsystems.
- Format: UDT_Function or purpose of the UDT
- Examples:
 - Inventory tracking tag UDT_InventoryTracking
 - Clean in place system UDT_CIP

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- 6. Add-On Instructions
 - An Add-On Instruction encapsulates commonly used functions or device controls.
 - It is not intended for use as a high-level hierarchical design tool.
 - Once an Add-On Instruction is defined in a project, it behaves similarly to the built in instructions that are already available in the programming software.
 - The Add-On Instruction appears on the instruction toolbar and in the instruction browser

VI. Develop Routine Logic Using State Logic Programming Methods



- State Programming
 - Ladder logic program is based on the different states or modes of operation of the system being controlled
 - Process of viewing process or machine operation in terms of states as defined by the outputs, and transitions as defined by the inputs.

States of a Process



- When a PLC controlled machine is performing its intended function(s), the status of its outputs will define its mode, or *state*, of operation.
- States
 - Modes of operation where the machine is performing an identifiable activity that has to be initiated and then stopped.

State Transitions



- Input status facilitates the *transition* from one state to another.
- States
 - Defined by the outputs
- Transitions
 - Defined by condition (Inputs/Timers/Counters)

State Diagrams



 Graphically displays the various states and corresponding transitions between those states of the machine or system being controlled.



State Logic Programming Steps



- 1. Identify and document the system states on a state diagram
- 2. Identify and document the system transitions on a state diagram
- 3. Create the state table

State Logic Programming Steps



- 4. Write the program state ladder logic per the state table
 - a. Define each *active state* as an Examine_ON input condition with a unique "internal" address.
 - b. Create a rung for each output.
 - c. Use the appropriate state Examine_ON input condition to activate the appropriate output.
 - If more than one state activates an output they are to be ORed together on that rung.



- 5. Write the program transition ladder logic per the state diagram
 - a. Transition lines into the state bubble of the state diagram are Examine_ON (or same as transition state) input conditions.
 - b. Transition lines out of the state bubble of the state diagram are Examine_OFF (or opposite of transition state) input conditions that are ANDed with the lines into the bubble.
 - c. Multiple transition lines into the state bubble should be ORed.
 - d. Multiple transition lines out of the state bubble (with the same transition Input address) that lead to another state may require a counter or timer to differentiate the logic paths.



6. Add process interrupt logic to the program

- Nested States
 - States that can only exist if another (higher state) exists
 - Example Hydraulic cylinders only work if hydraulics are turned on!

State Table



State	Outputs						
	Red_Lt	Green_Lt	Yellow_Lt	Blue_Lt	Motor		